

Department of Mechanical Engineering  
 Indian Institute of Technology Delhi  
 MCL731: Analytical Dynamics

Time: 9.30 am-10.30 am

Minor Test - I

Maximum Marks: 20

**Instructions**

Use of any electronic devices not permitted; Do not share pencil, eraser, ruler; Assume appropriately any missing data

**Section A**

1. A particle of mass  $m$  can slide down on a smooth rigid wire having the form  $x^2 = 4ay$ , where gravity acts in the direction of negative  $y$  axis. Using D'Alembert's principle and the equation of constraint, show that  $2a\ddot{x} + x\ddot{y} + g = 0$  [05]

2. In Fig. 1, two particles having masses  $m$  and  $2m$  are connected by a massless rod of length  $\sqrt{2}r$  to form a dumbbell. It can slide without friction in a circular bowl of radius  $r$ . Use the principle of virtual work to obtain the value of  $\theta$  at the position of static equilibrium. [05]

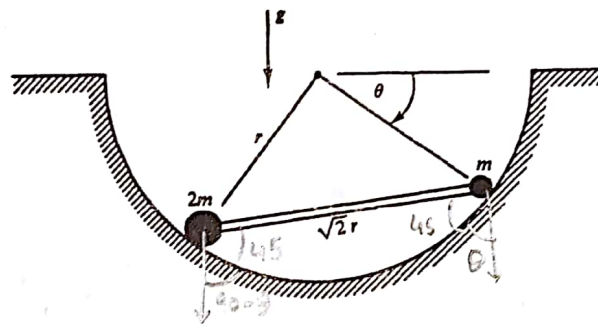


Fig. 1: Question 2

3. A vector  $\vec{P}(t) = 6t\hat{e}_1 - 3t^2\hat{e}_2 + 6\hat{e}_3$  units is referred to a reference frame  $B = \{O'; \hat{e}_1\hat{e}_2\hat{e}_3\}$  which has a constant angular velocity  $\vec{\omega} = 3\hat{e}_1 + 2\hat{e}_2 + 6\hat{e}_3$  units relative to another frame  $A = \{O; \hat{i}\hat{j}\hat{k}\}$ . Find the time rate of change of  $\vec{P}(t)$  apparent to observers in the two frames, and referred to  $\hat{e}_1\hat{e}_2\hat{e}_3$  basis of  $B$ . [03]

**Section B**

4. Write the expression for Coriolis acceleration in vector form and give the kinematic meaning of the vectors used in your expression. [02]

5. Explain why obtaining the equations of motion (in Cartesian coordinates) of a spherical pendulum using D'Alembert's principle together with the constraint equation is relatively easier than using Lagrange's equations of motion of the first-kind together with the same constraint equation. [01]

6. Give an example of a workless constraint with a neat sketch and reasoning. [02]

7. Is the kinematic constraint between two gears holonomic or nonholonomic? Give reasons. [02]