Venue: Home

Odd Semester 2021-2022

20 September 2021

## Department of Mechanical Engineering Indian Institute of Technology Delhi MCL731: Analytical Dynamics

Time: 9.00 am-10.45 amMinor TestMaximum Marks: 5	Гіте: 9.00 am-10.45 am	Minor Test	Maximum Marks: 30
--	------------------------	------------	-------------------

## Instructions

Use of any electronic devices not permitted; Follow academic honor code; Assume appropriately any missing data

- 1. Derive Lagrange's equation of motion of the second kind from D'Alembert's principle for a holonomic system without constraints
- 2. Consider a simple pendulum of mass m and length l constrained to move in the xy plane. Gravity acts along negative y-axis. Is the system conservative or non-conservative? Give reasons.
- Explain why obtaining the equations of motion (in Cartesian coordinates) of a spherical pendulum using D'Alembert's principle together with the constraint equation is relatively easier than using Lagrange's equations of motion of the first-kind together with the same constraint equation. [01]
- 4. Given a physical system with a Lagrangian function  $L = \frac{1}{2}m(\dot{x}^2 + \dot{y}^2 + \dot{z}^2 + 2\beta z)$  and a constraint  $a\dot{x} + b\dot{y} + c\dot{z} = 0$  where x, y, and z are the generalized coordinates and  $\beta$ , a, b and c are some non-zero constants.
  - (a) Solve for  $\ddot{x}$ ,  $\ddot{y}$ , and  $\ddot{z}$  in terms of the symbols introduced above. [04]
  - (b) Solve for the constraint forces.
- 5. Referring to Fig. 1, write the nonholonomic constraint equation/s involving the generalized coordinates  $x, y, \theta$  and  $\phi$ . Angle  $\theta$  is the angle between the disk axis and x-axis. [03]



Fig. 1: Vertical rolling disk on a horizontal plane.

6. A particle is constrained to move along a equiangular spiral  $r = ae^{b\theta}$  so that the radius vector moves with constant angular velocity  $\omega$ . Determine the velocity and acceleration components in terms of  $a, b, \omega$ , and t.

[04]

[04]

[01]

[03]

- 7. In Fig. 2, two particles each of mass of m are connected by a rigid massless rod of length l. Particle 1 can slide without friction on a fixed straight wire. Using  $(x, \theta)$  as generalized coordinates, find expressions for the kinetic energy and the generalized momentum  $p_{\theta}$
- 8. A particle of mass m can slide without friction in a straight slot cut in a horizontal turntable (Fig. 3). The turntable rotates at a constant angular velocity  $\Omega$  about a vertical axis through its center at O. The coordinate y represents the position of the particle relative to the turntable and is equal to zero when the spring is unstressed and the particle is at minimum distance R from the center O. Use the Lagrangian method to the differential equation of motion. Identify the terms generated by  $T_2$ ,  $T_1$ ,  $T_0$ , and V.



Fig. 2: Constrained dumbell.



Fig. 3: Mass in a groove.

[04]

[06]